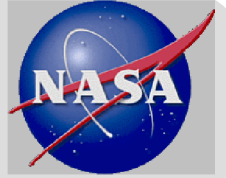


# **AN Overview of NASA's Orbital Debris Engineering Model**

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# Engineering Models

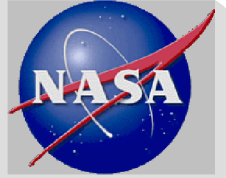


- **Orbital debris engineering models are mathematical tools to assess orbital debris flux**
  - **Created primarily for spacecraft designers to accurately assess spacecraft risk**
  - **Also have been used historically to estimate sensor flux (e.g., predicted counts in a radar beam)**

## **Need to be updated periodically**

- **New data**
  - **New techniques**
  - **Unanticipated changes in the environment**
  - **Need for expanded capabilities**
- **Need to predict some distance into the future**

# Engineering Model History



- **Pre-1990 – simple flux curve based mostly on model results**

**1994 Space Station Freedom model and ORDEM96 – used new Haystack data to describe 1 cm – 10 cm regime accurately for the first time**

- **Finite inclination and eccentricity bands still described by analytic formulae**

**ORDEM2000 – used new techniques and computer improvements to describe complicated orbit distributions**

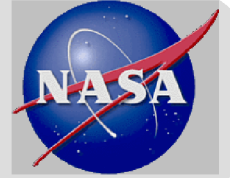
- **Populations now saved as digital populations rather than analytic functions**

# ORDEM2010 New Features



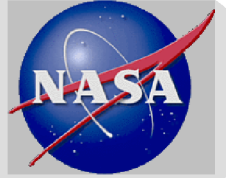
- **Expanded environment past LEO**
  - New GEO data
  - Allow elliptical spacecraft orbits
  - Requires expanding flux directionality
- **Include uncertainties**
  - Primarily uncertainties in population estimates
  - Need to propagate to final flux values
- **Include material density types**
  - Material densities influence damage equations
- **Debris shape was analyzed carefully, but is not explicitly included in the model**

# Structure



- **ORDEM2000**
  - Used finite element cells to describe spatial density in space around Earth
    - Altitude
    - Latitude
    - 2-dimensional velocity (parallel to Earth's surface)
    - Size
    - Time
  - 6 dimensions of data storage
- **ORDEM2010**
  - In order to extend beyond LEO, need to add radial velocity term
  - Breaking up population into material types adds another dimension
  - 8 dimensions of data storage!
  - **Solution - store orbit populations in terms of orbital elements**
  - Altitude + Latitude + 3D Velocity
    - Perigee Altitude + Eccentricity + Inclination
  - This trades off storage space (6D) with run time

# Structure

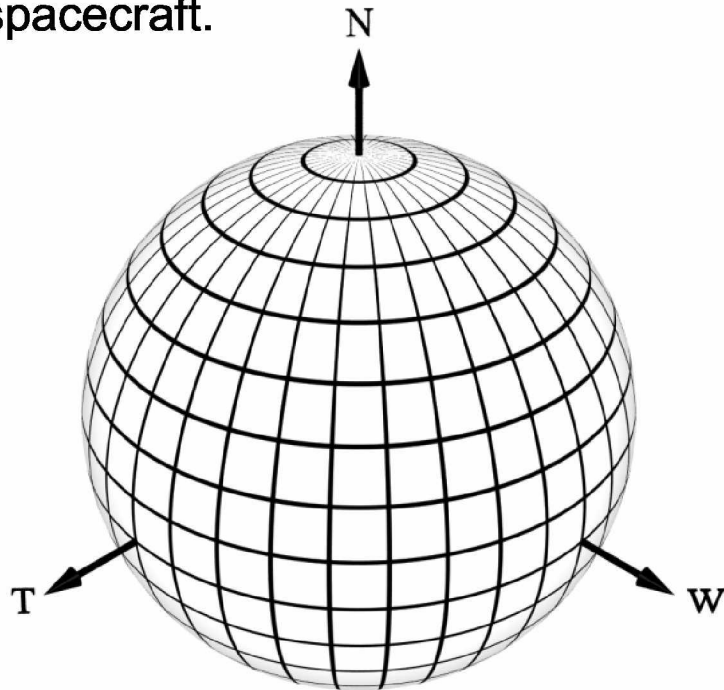


- **Fluxes are computed at reference sizes and intermediate values interpolated ( $10\ \mu\text{m} - 1\ \text{m}$ )**
  - **ORDEM2000 – one reference size per decade (6 steps)**
  - **ORDEM2010 – one reference size per half decade (11 steps)**
- **5 discrete material populations**
  - **RORSAT Sodium-Potassium coolant droplets ( $1\ \text{g/cm}^3$ )**
  - **Intact objects ( $>10\ \text{cm}$ ,  $2.8\ \text{g/cm}^3$ )**
  - **Low-density debris ( $1.4\ \text{g/cm}^3$ )**
  - **Medium-density debris ( $2.8\ \text{g/cm}^3$ )**
  - **High-density debris ( $8.0\ \text{g/cm}^3$ )**
- **3 dimensional Orbital parameter finite element bins**
  - **Perigee Altitude**
  - **Eccentricity**
  - **Inclination**

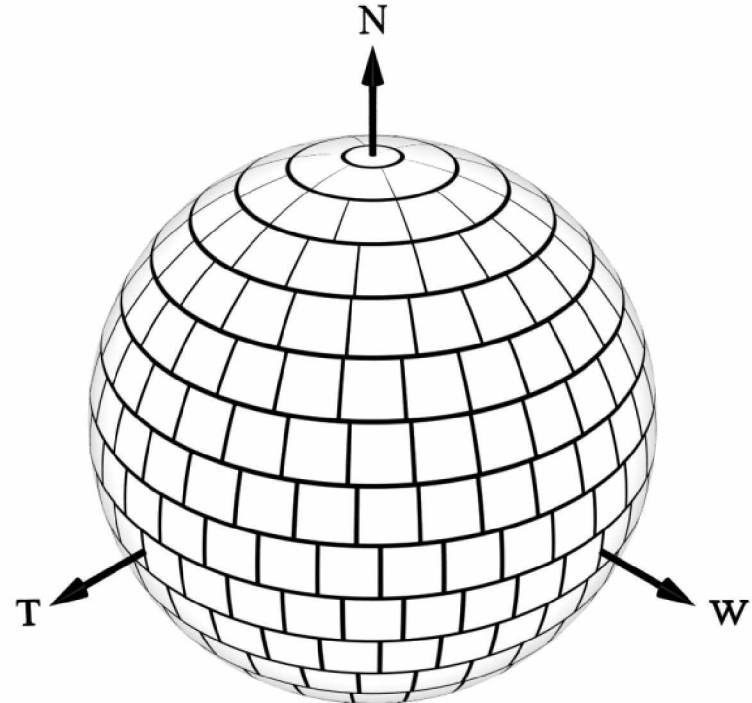
# Spacecraft Flux Computation



Spacecraft flux uses the concept of the encompassing “igloo” finite elements. Dimensions are “pitch/latitude”, “yaw/longitude”, and relative velocity in the frame of the spacecraft.

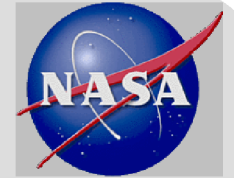


Equal-angle Igloo



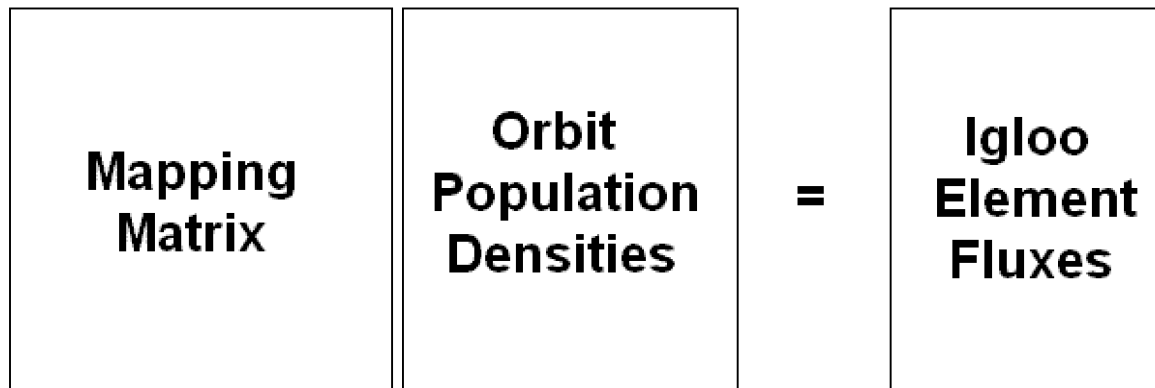
Equal-area Igloo

“Telescope mode” uses a much simpler 1-dimensional igloo in altitude



# Mapping Matrix

- There exists a mapping matrix that converts the orbital population finite element bins to “igloo” flux finite element bins
- This matrix must be computed numerically, but is independent of material type, size, etc. It is only dependent on the details of the spacecraft orbit / telescope pointing mode
- This mapping matrix is used to map population uncertainties into flux uncertainties



$$\sum_j M_{ij} P_j = I_i$$

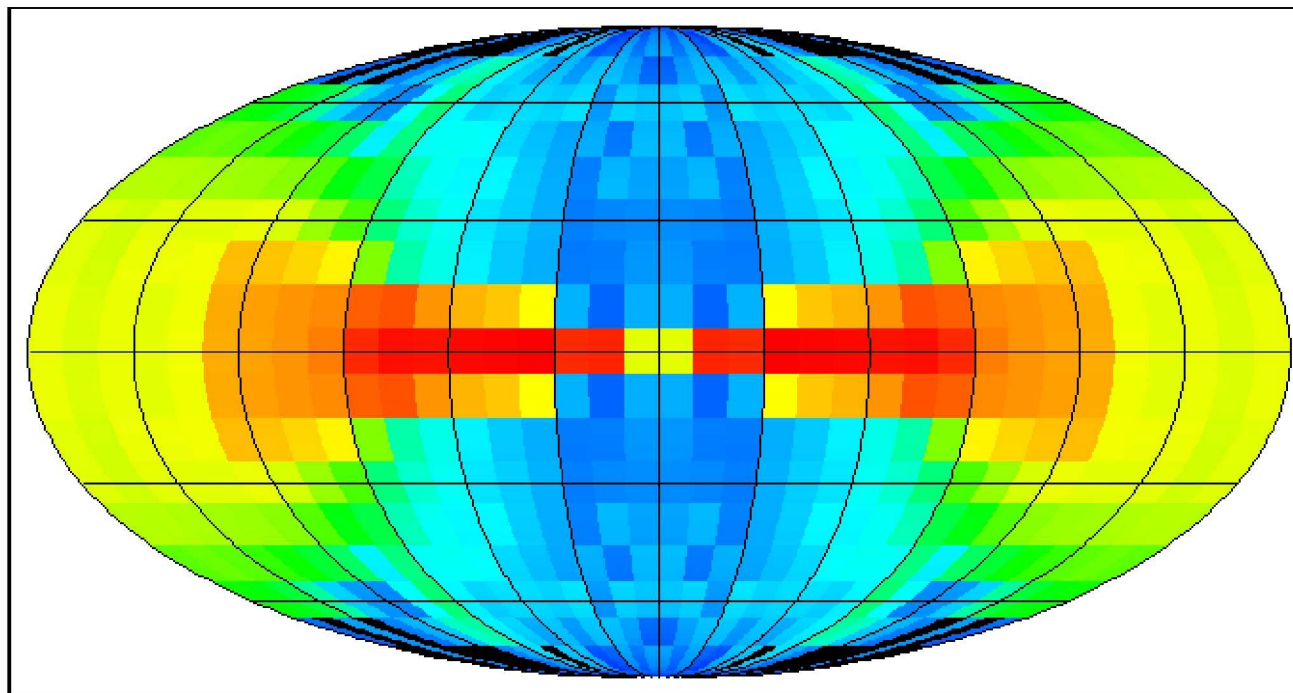


# ORDEM Igloo Fluxes – Mollweide Plot



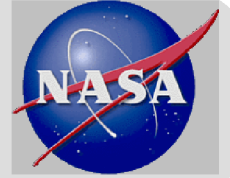
2-D Directional Flux

Year: 2003 a = 6778.136 e = 0.000000 inc = 51.60 particle size = >1cm



- Each direction bin is also subdivided into velocity bins
- Center of 2-D chart is yaw/pitch = 0/0 – the spacecraft direction

# Data

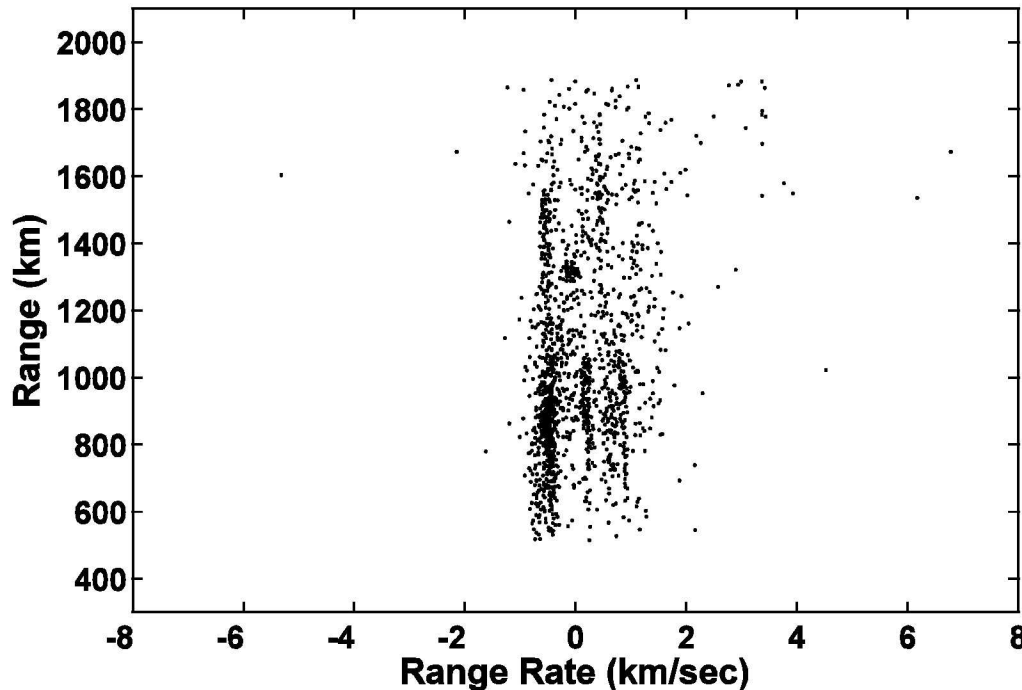


- **The computed orbit populations are empirically driven as much as possible**
- **> 10 cm : data is based on the catalog work of the US Space Surveillance Network**
- **1 mm – 10 cm : data is based on measurements by the Haystack and HAX radars, and supplemented by the Goldstone radar. Shape/material information from ground tests, especially SOCIT4**
- **10 mm – 1 mm : data is based primarily on Shuttle window and radiator impacts (material information included)**
- **GEO (>10 cm) : data based on MODEST optical telescope analysis**
- **Chinese ASAT test and Iridium-Cosmos cloud populations explicitly added based on empirical radar data analysis and modeling of future cloud evolution**

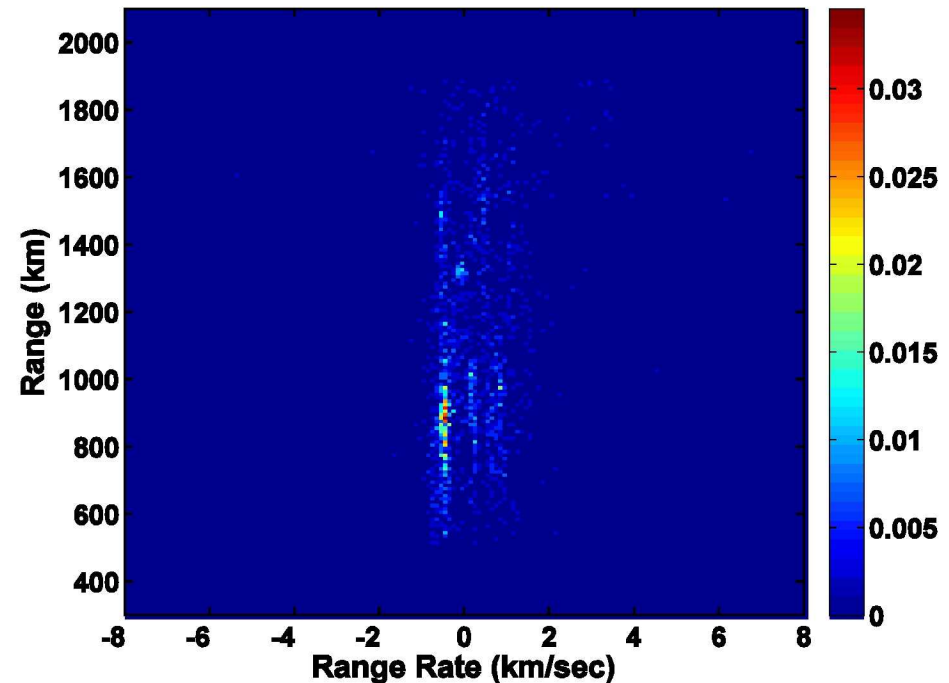
# Haystack Data



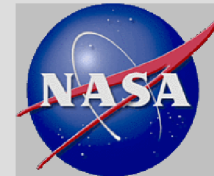
NoNak 2007 Haystack 75°East WFC4  
obs.hrs: 405.1 # of detect.: 1588 (size: 0.01-0.1m)



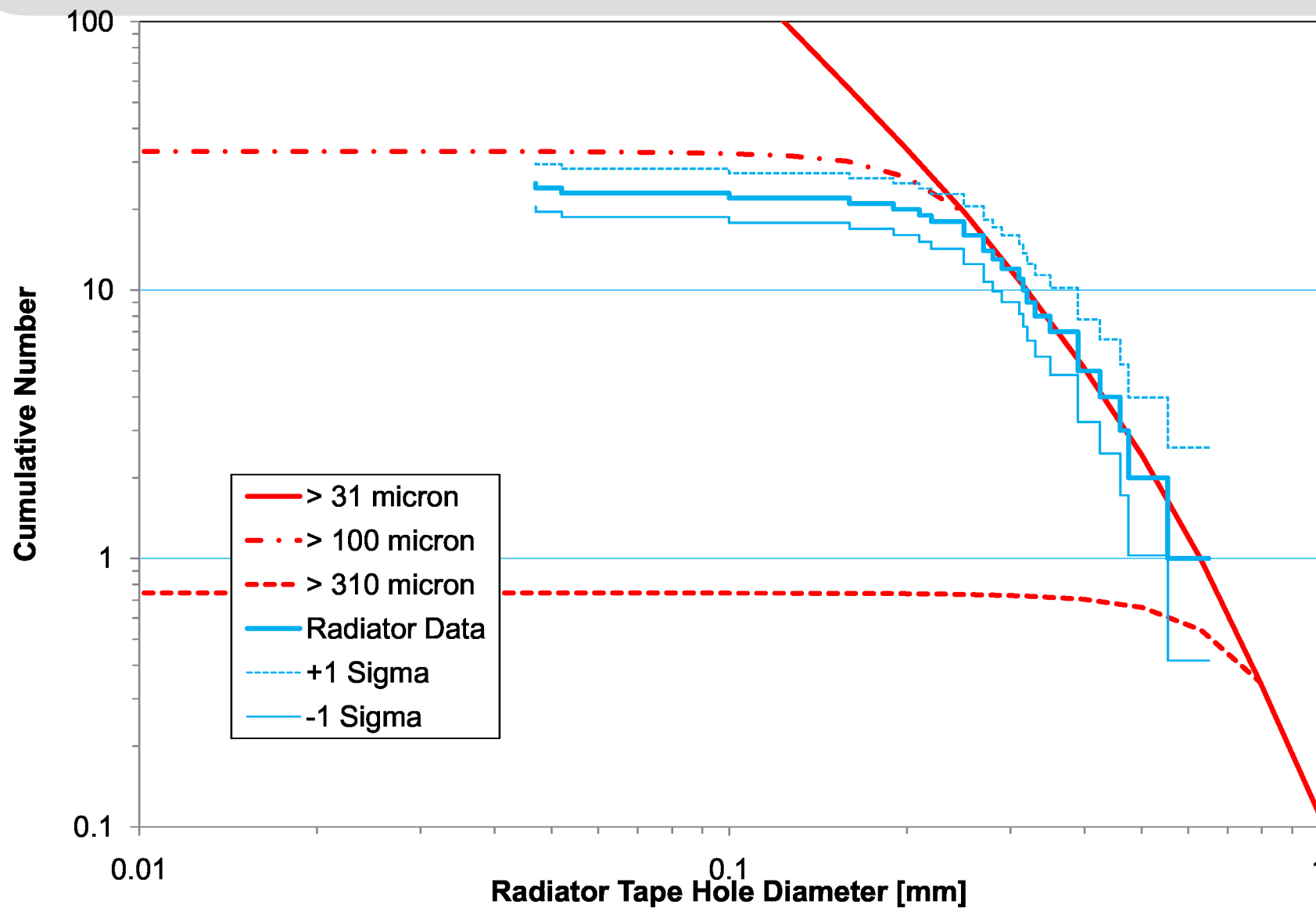
NoNak 2007 Haystack 75°East WFC4 (blns: 10km, 0.1km/sec) *Detect. Rate*



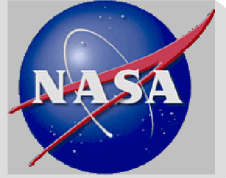
- A Bayesian method is used to adjust population parameters so that the predicted pattern of data (in this case range and Doppler range-rate) best match the data. Uncertainties are a by-product of this analysis



## Radiator Fit - HD data only



# Future Populations



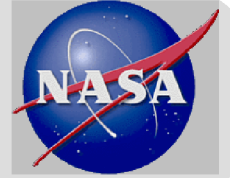
- **ORDEM2010 populations are projected out to 2035**

**Future populations based on LEGEND model runs using nominal assumptions for breakup rates, launch rates, and solar activity**

## **100 Monte Carlo runs**

- **Mean represents “average” future**
- **Spread in results represents range of possible futures, treated as uncertainty value**

# Uncertainties



- **Great effort was put into estimating and tracking uncertainties in the ORDEM2010 populations**

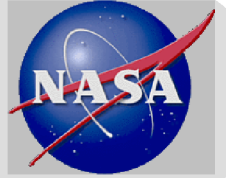
**For simplification, uncertainties are of two types – random (uncorrelated) and population (correlated) uncertainties**

- **Random uncertainties are those that are uncorrelated between different orbit value finite element bins within a population**
- **Population uncertainties are those correlated across the total sub-population**

- **Uncertainties in estimating populations from measurements**

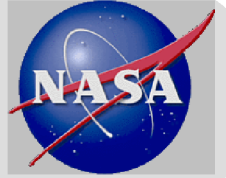
- **Conversion of measurements to size**
- **Material distributions (Multinomial errors)**
- **Distributions in orbital parameters (Poisson-like errors)**
- **Total Population in orbit family (Poisson-like errors)**
  - **These last two are handled by a multidimensional Bayesian method taking advantage of the Poisson nature of the measurements**

# Uncertainties



- **Modeling uncertainties**
  - **Future projections (Monte Carlo)**
- **Uncertainties in model construction**
  - **Orbit distributions created from discrete “objects” (Monte Carlo)**
  - **Numerical integration errors – orbit distributions must be numerically mapped to “igloo” using mapping matrix**
- **Uncertainty values are preserved for each “igloo” bin in final output files for use by user**

# Conclusions



**ORDEM2010 represents the latest generation of orbital debris engineering models**

- **New features:**
  - **Extension beyond LEO**
  - **Full 2D directionality for spacecraft flux**
  - **Material density breakdowns**
  - **Computes uncertainties in flux calculations**